

In the Claims:

1 1. (currently amended) A method for multiple object
2 recognition on an image pixel plane of received images (1),
3 said method comprising the following steps:

4 (a) roughly classifying (10) all pixel points of said
5 received images whether or not a pixel point is
6 relevant for said multiple object recognition to
7 provide relevant pixel points and eliminate irrelevant
8 pixel points;

9 (b) forming a reduced image (11) based on said relevant
10 pixel points as roughly classified in step (a);

11 (c) filtering (20) each reduced image (11) for forming at
12 least two filtered images (21, 22, 23) whereby image
13 components relevant for said multiple object
14 recognition are retained in said at least two filtered
15 images;

16 (d) further classifying (30) said at least two filtered
17 images for providing classified images, wherein said
18 further classifying is performed by a group ~~or~~
19 ~~ensemble~~ of different classifiers which operate in
20 accordance with learned rules to allocate said
21 classified images to different object classes, wherein
22 each classifier of said group of different ~~of said~~
23 classifiers operates based on a characterizing vector
24 forming an input information for its respective
25 classifier and wherein each different classifier works

independently of any other classifier of said group of
different classifiers;

- (e) merging ~~or fusing~~ (40) said classified images in accordance with an algorithm to ~~form~~ perform a combined global evaluation ~~or decision~~ for each class of said different object classes, ~~said global evaluation or decision representing~~ for providing merged images (41A, 41B, 41C); and
- (f) deciding (50), on the basis of said merged images, whether a pixel point of all remaining pixel points is still relevant and if so to which of said different object classes each relevant pixel point belongs.

2. (original) The method of claim 1, further comprising providing a set of predetermined first criteria for performing said rough classifying step (a), and providing a second set of second predetermined criteria for performing said filtering step (c).

3. (original) The method of claim 1, further comprising acquiring vicinity image data representing a vicinity of a respective relevant pixel point of a corresponding filtered image, and forming said characterizing vector from said vicinity image data.

4. (original) The method of claim 1, further comprising providing different weighting factors or evaluation numbers representing different classes of objects to be recognized,

4 and assigning or allocating certain weighting factors or
5 evaluation numbers of said different weighting factors to
6 each relevant pixel point thereby marking each relevant
7 pixel point with regard to which of said different classes
8 of objects the marked pixel point belongs.

1 5. (original) The method of claim 3, wherein said step of
2 acquiring said vicinity image data comprises sorting said
3 vicinity image data in a spiral pattern into a vector of
4 coefficients, applying a rapid Fourier transformation to
5 said vector of coefficients to form transformation
6 coefficients and forming said characterizing vectors of an
7 absolute value of said transformation coefficients.

1 6. (original) The method of claim 1, further comprising using,
2 as said group of different classifiers, a neural network
3 capable of learning for performing said step of further
4 classifying (30).

1 7. (original) The method of claim 6, further comprising
2 selecting from relevant pixel points of said filtered
3 images (21, 22, 23) characterizing or feature vectors
4 representing features of said relevant pixel points of said
5 rough classifying (10), and forming rules for said neural
6 network from said characterizing or feature vectors.

1 8. (original) The method of claim 1, further comprising
2 performing said merging step in accordance with a
3 statistical process for obtaining said global evaluation,
4 and further comprising using in said statistical process
5 information based at least on one of a type, position and
6 ³ content of said received images (1) to be evaluated.

1 9. (original) The method of claim 1, further comprising
2 representing recognized objects by pixel clusters in an
3 image (51) that represents a decision regarding said
4 combined global evaluation while performing said deciding
5 step (50).

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